Automated Synthesis of Generalized Invariant Strategies via Counterexample-guided Strategy Refinement

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 - P-complete, computing winning regions for winning memoryless strategies
- We focus on synthesizing generalized strategies to tackle the state-space explosion problem

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- e.g., the two-pile Nim game



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- A practical synthesis algorithm, based on the idea of invariant and counterexample-guided synthesis

Outline

Representation framework

- how to represent a game problem
- how to represent a generalized strategy
- formalize the correctness
- 2 Automated synthesis algorithm
 - practical verification with invariants
 - counterexample-guided strategy refinement
 - experiments and results

Initial database:

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A BAT represents a class (possibly infinitely many) of games

Definition

Given a game BAT \mathcal{D} , we define the finite-state axiom \mathcal{D}_{fs} as the formula $\exists k \forall s.exec(s) \supset B(k,s)$, where B(k,s) is the conjunction of the following formulas:

- **①** $\forall \vec{x}.\vec{x} > k \supset \neg F(\vec{x},s)$, for each relational fluent *F*;
- ② $\forall \vec{x}.\vec{x} > k \supset f(\vec{x},s) = 0$, for each non-unary functional fluent;
- **③** $\forall \vec{x}.f(\vec{x},s) ≤ k$, for each functional fluent *f*;
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We assume that $\mathcal{D} \models \mathcal{D}_{fs}$

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Example

 $N\%2 = 0?; \pi a.a; N\%2 = 1?$

Safe postdiction Strategies

Composite strategy δ^{*}_S: [turn(p)?; S | ¬turn(p)?; πa.a]*

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Definition

Given a game problem $P = \langle D, p, \phi \rangle$ and a postdiction strategy S for player p, we say that S is a solution to P if

 $\mathcal{D} \models \forall s \forall \delta. Trans^*(\delta_{\mathcal{S}}^*, S_0, \delta, s) \supset \phi[s] \land \exists s'. Trans(\delta_{\mathcal{S}}, s, nil, s').$

- Configuration: (δ, s)
- $Trans(\delta, s, \delta', s')$: a transition from configuration (δ, s) to (δ', s') in one step
- *Trans**: the reflexive transitive closure of *Trans*

Automated Synthesis

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- Invariant strategies: First-order verifiable
 - Intuition: maintain a *strong* first-order property, no matter how the opponent acts throughout the games
 - Approximation of a safe postdiction strategy, relaxing the requirement of reachability

Whenever it's *p*'s turn to move and φ holds, *p* can execute an action to enforce ψ:

$$\varphi \wedge turn(p) \models \bigvee_{i=1}^{N} \exists \vec{x}. \mathcal{R}[Poss(A_i(\vec{x}), s) \land \psi(do(A_i(\vec{x}), s))]_{\downarrow}$$

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2 Whenever it's the opponent's turn to move and ψ holds, any action the opponent can execute makes φ true:

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3 Both *ϕ* and *ψ* imply the safety condition *ϕ* **4** If $p = P_1$, $\mathcal{D}_{S_0\downarrow} \models ϕ$; otherwise $\mathcal{D}_{S_0\downarrow} \models ψ$

Synthesis Algorithm: General Picture



Counterexample-guided Strategy Refinement





Counterexample-guided Strategy Refinement



Counterexample-guided Strategy Refinement



 $b + \mathcal{D}_{S_0} \Longrightarrow \{s_0, s'_0, s''_0, \ldots\}$ $\{s_0, s'_0, s''_0, \ldots\} + \mathcal{D} \Longrightarrow \{g, g'', g''', \ldots\}$











Theorem

Given a game problem, if the algorithm returns a strategy, then it is a safe strategy.

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game	L	R+	R^{-}	В	S	T(s)
2-Nim	44	2	5	0	6	14.5
Take-away	94	3	11	1	6	43.2
Sub.	118	7	23	0	4	321.1
E.&D.	64	3	13	0	10	210.8
Mon. 2-Nim	44	1	9	0	6	26.4
Ch.2xN	44	2	12	0	14	35.6
Ch.NxN	58	-	-	-	-	-
Coloring	32	4	11	1	8	303.2
Leader	66	0	8	2	16	367.2

Table 1: Experimental results

• Generalized strategy synthesis problem for a set of games with safety goals

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- Invariant strategies, maintaining invariants no matter how the opponent acts
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- Expressive strategies, to solve richer domains, such as those whose formalizations need quantified formulas

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- Invariant strategies, simple structures, whose synthesis relies heavily on the synthesis of formulas
 - consider more complicated structures in strategies, such as finite-state automata (FSA)